

rotorcrafft-genom3 - Bug #155

Improve bad IMU calibration detection

2018-04-05 11:23 - Anthony Mallet

Status:	New	
Priority:	Normal	
Assignee:		
Category:		
Target version:		
Description		
<ul style="list-style-type: none">• Maybe compute norm(accelerometer) and ensure that it is close enough from 9.81• Complain harder if sensors are close to the saturation value (depends on the hardware)		

History

#1 - 2019-08-13 15:05 - Anthony Mallet

- Project changed from mikrokopter-genom3 to rotorcraft-genom3